Spider2-V: How Far Are Multimodal Agents From Automating Data Science and Engineering Workflows?

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Abstract

Data science and engineering workflows often span multiple stages, from warehousing to orchestration, using tools like BigQuery, dbt, and Airbyte. As vision language models (VLMs) advance in multimodal understanding and code generation, VLM-based agents could potentially automate these workflows by generating SQL queries, Python code, and GUI operations. This automation can improve the productivity of experts while democratizing access to large-scale data analysis. In this paper, we introduce Spider2-V, the first multimodal agent benchmark focusing on professional data science and engineering workflows, featuring 494 real-world tasks in authentic computer environments and incorporating 20 enterprise-level professional applications. These tasks, derived from real-world use cases, evaluate the ability of a multimodal agent to perform data-related tasks by writing code and managing the GUI in enterprise data software systems. To balance realistic simulation with evaluation simplicity, we devote significant effort to developing automatic configurations for task setup and carefully crafting evaluation metrics for each task. Furthermore, we supplement multimodal agents with comprehensive documents of these enterprise data software systems. Our empirical evaluation reveals that existing state-of-the-art LLM/VLM-based agents do not reliably automate full data workflows $(14.0\%$ success). Even with step-by-step guidance, these agents still underperform in tasks that require fine-grained, knowledge-intensive GUI actions (16.2%) and involve remote cloud-hosted workspaces (10.6%) . We hope that Spider2-V paves the way for autonomous multimodal agents to transform the automation of data science and engineering workflow. Our code and data are available at <https://spider2-v.github.io>.

1 Introduction

Data science and engineering pipelines usually rely on professional data software systems such as BigQuery, dbt, and Airbyte to acquire, process, and orchestrate large-scale data. Utilizing these enterprise systems involves writing SQL and Python code, as well as frequent and repetitive graphical user interface (GUI) controls, which can be complex even for experienced data scientists and engineers. With rapid advances in large language models (LLMs) and vision language models (VLMs), LLM/VLM-based autonomous agents have the potential to automate these work-

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Figure 1: Spider2-V is a multimodal agent benchmark spanning across complete data science and engineering workflows (*e.g.*, two task examples in the Figure above). It involves various professional enterprise-level applications and includes intensive GUI controls apart from code writing throughout the real-time multi-turn interaction with an executable computer environment.

flows [\[37,](#page-12-0) [32\]](#page-11-0), enhancing productivity for data scientists and engineers [\[38,](#page-12-1) [16\]](#page-11-1) while democratizing access to large-scale data [\[15,](#page-10-0) [40\]](#page-12-2).

Previous studies on data agents focused mainly on daily life data processing and analysis by generating code or API calls [\[42,](#page-12-3) [9,](#page-10-1) [4\]](#page-10-2), neglecting other crucial stages of data science and engineering (*e.g.,* data ingestion and integration) using enterprise applications (*e.g.,* Snowflake, Airflow, and Dagster). Additionally, to complete data workflows, data scientists and engineers often need to navigate multiple professional data systems, combining code writing with intensive GUI controls, such as navigating web pages and clicking buttons [\[5,](#page-10-3) [45\]](#page-12-4). However, there is currently no benchmark that integrates both code generation and GUI controls for professional data science and engineering.

To address this gap, we propose Spider2-V, the first multimodal agent benchmark covering the entire data science and engineering workflow, involving 494 real-world tasks in a real-time executable computer environment and 20 professional enterprise data software. Spider2-V aims to evaluate a multimodal agent's ability to perform professional data-related tasks by writing code and managing the GUI in enterprise data software systems, including data warehousing (*e.g.,* BigQuery), data ingestion and integration (*e.g.,* Airbyte), data transformation (*e.g.,* dbt), data analysis and visualization (*e.g.,* Superset), and data orchestration (*e.g.,* Dagster). These tasks are derived from real-world practices, such as official tutorials on professional applications and open-source data engineering projects (with two task examples presented in Figure [1\)](#page-1-0). We also supplement retrieval-augmented agents with official documentation and tutorials of these software systems to assess their capability to generalize and learn from these resources.

Each task in Spider2-V is defined within an executable computer environment based on OS-WORLD [\[34\]](#page-12-5), which allows multimodal agents to simulate human actions (*e.g.*, typing code or clicking buttons) in a realistic setting. Specifically, a multimodal agent can observe real-time imagestyle screenshots and text-style accessibility tree of professional data applications in the current workflow and execute its predicted actions in dynamic multi-round interaction with the computer. This environment is connected to the real-world Internet, allowing the inclusion of professional software requiring authentic user accounts (*e.g.,* Snowflake). To ensure reproducible and reliable experiments with this enterprise data software, 10 authors with computer science backgrounds developed 170 automatic task setup configurations and 151 customized evaluation metrics in total.

We experiment with state-of-the-art LLMs and VLMs including closed-source ones GPT-4 series [\[21\]](#page-11-2), Gemini-Pro-1.5 [\[26\]](#page-11-3), Claude-3-Opus [\[2\]](#page-10-4), QWen-Max [\[3\]](#page-10-5) and open-source representatives Mixtral-

8x7B [\[11\]](#page-10-6) and Llama-3-70B [\[20\]](#page-11-4). Performances reveal that even the top-tier VLM (GPT-4V [\[1\]](#page-9-0)) achieves only 14.0% success rate. In the most challenging subset, with action steps exceeding 15, the performance drops to 1.2% . And for those open-source LLMs, the success rate is less than 2% . This indicates that existing LLMs or VLMs are still far away from achieving full data workflow automation. Even provided with an oracle step-by-step plan, the overall performance only increases to 16.2%. This observation uncovers the poor capability of action grounding (*e.g.*, identifying the precise coordinates of elements in the current focused application window) for multimodal agents. Furthermore, extensive analysis (§ [4.3\)](#page-7-0) on Spider2-V demonstrate that these strategies remarkably promote the final performance, which include enhancing the alignment between different observation modalities, introducing feedback on action execution, integrating retrieved document context and enlarging the history trajectory length. These findings lay the groundwork for developing practical multimodal agents that can revolutionize the automation of data science and engineering workflows.

2 Executable Computer Environment of Spider2-V

In this section, we introduce the real-time executable computer environment of Spider2-V, which is built upon virtual machines (VMs) and adapted from OSWORLD [\[34\]](#page-12-5).

2.1 Task Definition

Generally, an autonomous data agent is modeled as a partially observable Markov decision process (POMDP). Given the current observation $o_t \in \mathcal{O}$ which includes a natural language instruction and a screenshot, accessibility tree (a11ytree), or their combination, an agent generates an executable action $a_t \in A$. This action can be clicking on a certain pixel of the screen (CLICK(560, 200)), or writing code through keyboard (TYPE("1s -1h")). The execution of a_t results in a new state $s_{t+1} \in S$ (*e.g.*, the updated computer state) and a new partial observation $o_{t+1} \in \mathcal{O}$. The a11ytree is a text-style representation of the desktop environment, which describes the status, position, and text content of each element (e.g., windows, buttons, and input boxes). The interaction loop repeats until an action that marks termination (DONE or FAIL) is generated or the agent reaches the max number of steps. See App. [D](#page-16-0) for more details about the observation space and action space.

2.2 Environment Setup

Figure 2: Five common operations to reset the initial environment.

To ensure that an agent starts from a consistent initial state, we invoke a series of function calls based on a pre-stored virtual machine (VM) snapshot to reset the environment. These function calls vary among tasks. And we summarize 5 universal categories with their functionalities (see Figure [2\)](#page-2-0), namely: 1) *File Transfer*: transfer files or project archives (either from local or cloud storage) into the VM; 2) *Application Launch*: open software on the desktop, *e.g.,* Visual Studio Code and Chromium; 3) *Remote API Calls*: invoke tool-specific API calls for professional applications, especially those requiring authentic user accounts, to reset and configure cloud workspaces; 4) *Script Execution*: execute a shell script in VM to set up the initial state, *e.g.,* run a Docker container to start a localhost webserver for Superset; 5) *Playwright Automation*: run web browser simulation with Playwright, *e.g.,* sign into an account or click a specific button and redirect to the target web page.

2.3 Task-specific Evaluation

Figure 3: Three generic methods for task evaluation.

After the interaction terminates, we only have access to the open-ended resulting state of the computer. Thus, to measure whether the goal of each task is accomplished, we write task-specific functions to retrieve the desired result from the open-ended resulting state and return the success flag $(0/1)$. In total, Spider2-V contains 170 initial state configurations and 151 evaluation scripts, respectively. And we classify all evaluation methods into 3 generic categories, also shown in Figure [3:](#page-3-0)

- a) *File-based comparison*: this method finds and copies the target files from VM to the host, and resorts to file-type based metrics (e.g., .json, .csv, etc.) to compare the specified aspect of the generated file with ground truth. Sometimes, the ground truth may be updated over time. In this case, we will fetch the latest labels from the Internet during evaluation.
- b) *Information-based validation*: this scheme is usually utilized to extract and check desired information from the computer. For example, in Figure [3\(](#page-3-0)b), we want to confirm whether the time schedule of the data transportation is correctly configured in Airbyte. We can invoke Airbyte APIs to retrieve, or Chromium Playwright to locate the target value.
- c) *Execution-based verification*: to verify whether an expected goal is achieved, we may also need to first execute a complicated Shell script in the final VM. For example, in Figure [3\(](#page-3-0)c), we manually trigger the target Airflow DAG^{[2](#page-3-1)} and check the eventual status through running logs.

3 Benchmark Construction

In this section, we introduce the general annotation pipeline, document warehouse construction, and dataset statistics for Spider2-V. For concrete examples, refer to App. [F.](#page-21-0)

3.1 Annotation Pipeline

To construct tasks in different categories, we find that official tutorials of enterprise applications serve as an excellent starting point. The 6-step annotation pipeline is illustrated in Figure [4\(](#page-4-0)a), and we elaborate it with a concrete and real example "Orchestrate dbt Core jobs with Airflow and Cosmos"^{[3](#page-3-2)}:

- 1) Collect tutorials: firstly, we find tutorials from official websites for each professional tool in Figure [5.](#page-5-0) In total, 10 annotators collected 217 source URLs. Note that these tutorials may utilize other professional software, e.g., MySQL. All involved professional tools are listed in App. [B.](#page-13-0)
- 2) Learn tutorials: the annotator selects one tutorial, learns and realizes it in the VM. After that, they can summarize key knowledge points from this tutorial. For example, in Figure [4\(](#page-4-0)b), five key steps in integrating a dbt project into an Airflow task are extracted.

²A DAG in Airflow is defined as a collection of tasks to run, and DAG_ID is used to uniquely identify it. ³The selected Airflow tutorial URL: <https://www.astronomer.io/docs/learn/airflow-dbt>

Figure 4: General annotation pipeline with one selected demonstration from the official Airflow tutorial: *Orchestrate dbt Core jobs with Airflow and Cosmos*.

- 3) Write instructions: since the chosen tutorial is extremely complicated, the annotator can select a few key points to construct the task instruction. In Figure [4,](#page-4-0) we only select key steps *iv)* and *v)* to write two versions of instructions, *abstract* and *verbose*, indicating different levels of proficiency. Note that, to avoid potential data contamination and make the task more realistic, we ask the annotator to introduce at least two modifications to the raw tutorial. In this example, we a) replace the original "my_simple_dbt_project" into an open-source dbt project called "jaffle-shop"^{[4](#page-4-1)}, and b) add one extra requirement on the time schedule (10:00 a.m. daily).
- 4) Write environment setup functions: the next step is to write initialization functions using operations defined in § [2.2.](#page-2-1) In the example above, we need to: a) Upload an unfinished $Airflow$ project into the VM. b) Execute a Shell script to launch the web server (via Docker containers) for Airflow under the project folder. c) Open all relevant applications on the desktop to simulate real user scenarios. d) Use Playwright to auto-login to the default Airflow account.
- 5) Write task-specific evaluation functions: In this step, annotators are required to programmatically obtain results from the open-ended states of VM and assess whether the task is completed using methods in § [2.3.](#page-3-3) In this example, the evaluator contains: a) manually run the target Airflow DAG and verify the final status is "success"; b) using Airflow CLIs to retrieve details of the target Airflow DAG, and compare dbt sub-tasks, status and schedule with ground truth.
- 6) Cross-validate on VM: to ensure correctness, we go through strict cross-validation. Each annotated task is sent to two other annotators to check: a) whether the chosen task reflects a real-world use case; b) whether verbose instruction accurately fulfills the task and its requirements in the abstract instruction; c) whether the environment can be reset to the same state in different trials; d) whether the evaluation is robust when we exactly follow the verbose instruction or modify some inconsequential steps; e) whether the evaluation score is 0 if we deliberately make some mistakes (red-teaming). The task is preserved only if it withstands all these tests.

On average, the annotation of one task (including cross-validation) costs roughly 4 hours.

3.2 Document Warehouse

Even senior data scientists query official documentation of professional applications when completing a complicated data engineering task. To compensate for the deficiencies of the data agents in utilizing enterprise professional software (e.g., unaware of coding specifications or APIs), we build a document warehouse for Spider2-V. Concretely, we recursively crawl the web pages from the root websites of the professional applications in Figure [5.](#page-5-0) After pre-processing through heuristics (refer to App. [C\)](#page-13-1),

⁴URL of open-source dbt project "jaffle-shop": <https://github.com/dbt-labs/jaffle-shop>

raw HTML web pages are convert into 3 different formats for retrieval, namely a) pure text, b) markdown, and 3) simplified HTML. Eventually, we obtain 11, 231 documents in total.

3.3 Dataset Statistics

Table 1: Statistics of Spider2-V.

Avg. Number of Used Apps Per Task

Figure 5: Task categories with professional tools.

Figure 6: Distribution of action steps, instruction length, and related applications per task.

Tasks We classify all 494 tasks in Spider2-V into 7 categories and 11 software sub-categories with main statistics in Figure [5](#page-5-0) and Table [1.](#page-5-1) Specifically, most (280 tasks, 56.7%) involve CLI and GUI operations. And 34% examples request registering authentic software accounts. Since each task is associated with a detailed, step-by-step tutorial (verbose instruction), the entire task set can be categorized into three distinct levels based on the number of actions in these instructions. The proportion of easy, medium, and hard tasks is approximately $1:2:1$. According to the rightmost distribution depicted in Figure [6,](#page-5-2) most tasks necessitate the coordinated utilization of multiple professional applications, thereby establishing Spider2-V as a particularly challenging benchmark.

Comparison with existing benchmarks In Table [2,](#page-6-0) we compare Spider2-V with other agent benchmarks. Spider2-V incorporates generic computer control commands into the field of data science and engineering and is distinguished by these salient features: 1) a real-time executable environment. Instead of providing static input-output pairs, Spider2-V is equipped with a dynamic computer desktop such that agents can proactively explore it; 2) multiple enterprise software. We integrate 20 professional applications into the benchmark, which include not only tools installed on local hosts but also cloud-based enterprise services; 3) intensive GUI operations. Unlike traditional coding or data science domains, experienced data scientists frequently manipulate the UIs of those professional software to simplify the data workflow (*e.g.*, enabling a specific function on the UI page or visualizing the graph view of data inputs). In summary, Spider2-V focuses on the use of professional enterprise software with visual interface in an interactive computer environment.

4 Experiments and Analysis

In this section, we introduce the experiment settings, experimental results, and ablation study to assess the proficiency of current LLM or VLM based agents on Spider2-V benchmark.

Benchmark	Field	Exec. Env?	Ent. Serv.?	GUI Support?	# Apps/ Sites	# Exec.-based Eval. Func.	# Tasks
Spider [42]	Text-to-SOL					0	1034
DS-1000 [15]	Data Science	Х	Х	х		0	1000
Arcade [40]	Data Science	Х				Ω	1082
MLAgentBench [10]	Machine Learning				4	13	13
SWE-Bench [12]	Software Engineering	Х	Х	Х	12		2294
Mind2Web [5]	Web				137	0	2000
WEBLINX [19]	Web	Х	Х		155	0	2337
WorkArena [6]	Web						29
AndroidWorld [25]	Android				20	6	116
WebArena [45]	Web				5		812
OSWorld [34]	Computer Control		Х		9	134	369
Spider ₂ -V	Data Science & Engineering w/ Computer Control				20	151	494

Table 2: Comparison with existing agent benchmarks. Columns include the research field (Field), whether an executable environment is provided (Exec. Env.?), whether enterprise service is utilized (Ent. Serv.?), whether GUI actions are supported (GUI Support?) and some other statistics.

4.1 Environment Settings

Agent baselines The baseline method includes 3 schemes in zero-shot prompt learning: 1) Setof-Mark (SoM, [\[36\]](#page-12-6)): following OSWORLD [\[34\]](#page-12-5) and VisualWebArena [\[14\]](#page-10-10), we adopt heuristic methods to retrieve coordinates of visible elements from a11ytree (a text-format observation type) and draw indexed bounding box for these elements on the screenshot. We further insert these indexes into the pruned a11ytree to enhance the alignment between screenshot and a11ytree. 2) Execution Feedback (EF, [\[28\]](#page-11-7)): we append execution feedback messages of those actions which failed to be grounded in the environment due to unexpected errors. The two techniques mentioned above are elaborated in App. [D.3.1.](#page-18-0) 3) Retrieval-Augmented Generation (RAG, [\[8\]](#page-10-11)): we leverage the task instruction as the query vector, bge-large-en-v1.5 [\[33\]](#page-12-7) as the embedding model, and LlamaIndex [\[18\]](#page-11-8) framework as the retrieval to generate document context for each task example. Documents are pre-chunked into segments with maximum length 512 and tokens overlapping size 20. Top 4 segments are selected as additional context in the task prompt (detailed in App. [G.3\)](#page-31-0).

LLMs and VLMs We experiment with state-of-the-art LLMs and VLMs, including open-source representatives such as Mixtral-8x7B [\[11\]](#page-10-6) and Llama-3-70B [\[20\]](#page-11-4), and closed-source ones including Qwen-Max [\[3\]](#page-10-5), Gemini-Pro-1.5 [\[26\]](#page-11-3), Claude-3-Opus [\[2\]](#page-10-4) and GPT [\[1\]](#page-9-0) families (GPT-4o and GPT- $4V⁵$ $4V⁵$ $4V⁵$). With respect to the two open-source LLMs and QWen-Max, we utilize pure text-format a11ytree as the observation type on account of their incapability of image processing. For the remaining 4 VLMs which support vision input, we use aligned text and image (that is Set-of-Mark) as the observation type in main experiments. Unless otherwise specified, we set the temperature to 0.5 and top_p to 0.9, the history trajectory window size to 3, the maximum length of a11ytree to 5000 tokens, and the maximum output tokens to 1500 in each turn. Heuristically, we require the agent to complete the tasks within both 15 interaction turns and one hour, which suffices for most tasks 6 .

4.2 Main Results

In Table [3,](#page-7-1) we compare performances of different LLMs and VLMs. All results above integrate techniques of both execution feedback (EF) and retrieval-augmented generation (RAG) in § [4.1.](#page-6-3) Accordingly, we can summarize that:

1) Existing data agents are far from satisfactory in completing real-world data science and engineering tasks. Even state-of-the-art VLMs (GPT-4o and GPT-4V) perform terribly on Spider2-V, achieving at best 14.0% overall success rate. As for their strongest competitors,

⁵We utilize the version gpt-4o-2024-05-13 for GPT-4o and gpt-4-1106-vision-preview for GPT-4V.

⁶Although some tasks require more than 15 actions, we encourage the multimodal agent to predict multiple actions in one response in order to save the budget in the prompt design (see App. [G.1.2\)](#page-27-0).

Table 3: Success rates of baseline agents on Spider2-V grouped by 7 task categories (see Figure [5\)](#page-5-0), namely data warehousing (*ware.*), transformation (*trans.*), ingestion (*inges.*), visualization (*visual.*), orchestration (*orche.*), traditional data processing (*proc.*), and IT service management (*manag.*). For the first three LLMs, since they do not support visual information, we only utilize the text-based a11ytree as the observation. For the remaining four VLMs, we adopt Set-of-Mark (see § [4.1\)](#page-6-3).

LLM/VLM	Observation	Success Rate $(\%)$							
		ware.	trans.	inges.	visual.	orches.	proc.	serv.	Overall
Mixtral-8x7B	al lytree	$1.2\,$	0.0	0.0	0.0	2.6	0.9	0.0	0.8
Llama-3-70 B		2.4	0.0	0.0	2.5	3.9	2.8	0.0	2.0
Owen-Max		$1.2\,$	0.0	0.0	0.0	2.6	0.0	0.0	0.6
Claude-3-Opus	Set-of-Mark	2.4	2.5	10.4	15.0	11.5	3.8	12.1	8.1
Gemini-Pro-1.5		3.6	2.5	14.6	15.0	10.3	2.8	19.0	9.1
$GPT-40$		7.2	7.5	24.0	14.1	19.8	10.1	13.8	13.8
GPT-4V		10.8	10.0	12.0	25.0	18.4	8.5	12.1	14.0

Gemini-Pro-1.5 [\[26\]](#page-11-3) and Claude-3-Opus [\[2\]](#page-10-4), they attain worse performances, even less than 10% percents. There is still ample room for improvement in future work.

- 2) Closed-source models are much more superior than open-source ones. For those open-source LLMs, the success rate is exceedingly low, with some categories approaching zero. On one hand, it can be attributed to the fact that closed-source VLMs are pre-trained and fine-tuned on data of higher quality. On the other hand, closed-source VLMs support inputs with longer contexts and integrate both vision and text modalities (further analyzed in § [4.3\)](#page-7-0).
- 3) Performances of data agents exhibit high variance, especially in categories "*data ingestion*" and "*data visualization*". The majority of these two partitions are pure GUI tasks, which means agents mostly interact with the environment through time-dependent GUI operations. However, a minor error in one intermediate step can be amplified, resulting in the entire sequence of actions being wasted. Through error analysis on trajectories, we discover that once agents mispredict the coordinates of the correct button, they will open the wrong window and become trapped in the incorrect area, unable to return.
- 4) Across 7 data categories, the partitions "*data warehousing*" and "*traditional data processing*" are extremely challenging. The reasons for this observation are two-fold: a) *data warehousing* tasks mostly involve authentic user accounts (*e.g.*, BigQuery and Snowflake). Compared to other tasks which can be accomplished in a local host, these dynamic real-world scenarios incur extra burden on data agents, such as network connection delay and pop-up windows. Multimodal agents need to deal with these unexpected situations in real-time interaction with the computer. b) As for *traditional data processing*, the bottleneck is that spreadsheets in Excel contain many cells, and it is particularly difficult for data agents to accurately locate the coordinates of cells. For example, applying the same math formula to the entire column requests multimodal agents to firstly pinpoint the right corner of a specific cell, wait for the mouse to become a cross, press and drag the mouse towards the target cell. This series of actions requires precise and fine-grained GUI controls which are difficult to implement.

4.3 Analysis

In this section, we delve into different factors which influence the eventual success rates, and analyze the underlying logics. The following analyses are based on our agent baseline with VLM GPT-4o unless otherwise specified. Firstly, we split the overall results into different subsets in Table [4.](#page-8-0)

1) Tasks with more inherent action steps are more difficult. Each task is associated with one verbose task instruction which gives a step-by-step guidance on how to complete it. We count the number of actions in the verbose instruction and split the entire task set into 3 difficulty levels: $<$ 5 steps (Easy), $5 \sim 15$ steps (Medium), and > 15 steps (Hard). Not surprisingly, as the number of intrinsic action steps increases, the average performance decreases significantly. And for those extremely tough tasks, existing VLM-based data agents can hardly accomplish the goal.

Table 4: Success rate of GPT-4o with agent base-Table 5: Ablation study on action space, observaline SoM+EF+RAG across different partitions. tion types and 3 tricks in § [4.1](#page-6-3) on a task subset.

- 2) Tasks involving authentic user accounts are much more challenging. One salient feature of Spider2-V is the integration of professional applications that require authentic user accounts. We also split the entire task set accordingly (w/o or w/ account). Notably, data agents struggle to complete tasks involving authentic user accounts (10.6% success rate). These tasks deal with real-world scenarios and incorporate cloud-hosted enterprise services. Compared with Web servers which are launched locally in the VM (*e.g.*, from Docker containers), the cloud Web UIs 1) generally integrate more comprehensive functionalities or options in their menu panel, and 2) potentially suffer from emergency situation, such as extended network response delay due to bandwidth limitation or server overload. We conjecture these two causes collectively contribute to the inferior performances.
- 3) Incorporating GUI operations typically lead to improved performances. We split the task set by interfaces. If the task can be completed with pure CLIs (e.g., code editor or bash terminal), we classify it as cli. If the task only requires the agent to manipulate the GUI (usually on the Web page), we classify it into gui. For the remaining cases $(cli+gui)$, an agent must write code or scripts, and control the UI screen. We observe that pure gui tasks are much easier than cli tasks. This conclusion can be explained by the following two reasons: 1) GUIs of professional applications are designed to simplify the original coding task. Clicking buttons or typing values on UIs can avoid handling the rigorous and complex coding specification. 2) Both observation types, namely the screenshot and a11ytree, are naturally proposed for GUI tasks. For pure cli tasks, data agents must perform extra actions to locate and switch to the target panel before writing code.
- 4) Providing a step-by-step guideline in task instructions results in remarkable performance gains. The key difference between abstract and verbose instructions (the third step in § [3.1\)](#page-3-4) is whether a detailed step-by-step guidance is offered. With such stepwise oracle tutorials, data agents do not need to reason and plan, thus dramatically simplifying the original task. And the 4.8 points improvement in Table [4](#page-8-0) consolidates this hypothesis. Nevertheless, the low success rate with verbose instructions (16.2%) indicates that current VLMs still yield unsatisfactory results when purely grounding actions in real-world contexts. And significant potential remains for further enhancement.

In Table [5,](#page-8-1) we analyze the influence of different combinations of action space, observation types, and the 3 techniques described $\S 4.1$. The findings include: 1) **Regarding action space,** pyautogui code slightly outperforms self-customized JSON dict $(12.6\% \text{ vs. } 10.5\%).$ This can be attributed to the advantage that agents can also generate functional Python code like file traversal apart from the limited GUI control operations using the first action space. And it improves the efficiency of action grounding. 2) As for observation types, single screenshot leads to very low performances (4.2%) on account of the agent's failure in pinpointing concrete elements. When inserting a11ytree into the observation which contains precise coordinates, the agent capability of locating target pixels is remarkably promoted. 3) All 3 tricks we integrate into the agent baseline (namely SoM, EF and RAG) will boost eventual performances. It is interesting that if we do not adopt Set-of-Mark (that is, enhancing the alignment between two modalities of observations), the result of screenshot+a11ytree is even worse than that using pure a11ytree. This emphasizes the significance of modal alignment when handling state observations.

A moderate temperature and longer history window size improve performances. In Figure [7,](#page-9-1) we investigate the influences of two hyperparameters on a task subset: 1) The top-ranked performance is achieved with sampling temperature 0.5. 2) With the history window size enlarges, from 0 (no history, only the current observation) to 3, the performance in-

Figure 7: Ablation study on hyper-parameters.

creases stably. However, due to constraints on input length and considerations of cost-effectiveness, we are unable to extend the history trajectories any further. This also points out that the interaction efficiency is a serious issue and promising research direction.

5 Related Work

Benchmarks for data science and engineering In the field of data science and engineering, several recent works propose novel benchmarks to evaluate the capabilities of LLM agents in manipulating Excel spreadsheets [\[16,](#page-11-1) [4\]](#page-10-2), common data science libraries (*e.g.*, SQL and pandas) [\[42,](#page-12-3) [15,](#page-10-0) [9,](#page-10-1) [40\]](#page-12-2), machine learning [\[10\]](#page-10-7) or software engineering [\[16\]](#page-11-1) projects. They are usually confined to a single stage within the entire data pipeline, predominantly data processing and analysis, thus overlooking other stages such as data warehousing and orchestration from a broader perspective. Besides, like other coding-related datasets [\[38,](#page-12-1) [29,](#page-11-9) [41\]](#page-12-8), they merely focus on the command line interface, neglecting the fact that enterprise software usually has rich graphical user interfaces (GUIs). And data scientists often combine code programming with intensive GUI operations to fulfill a data workflow. To this end, Spider2-V is proposed as the first-of-its-kind multimodal agent benchmark in the field of data science and engineering, which covers the entire data workflow and integrates visual interfaces.

Benchmarks for multimodal agents Existing works on GUI interaction mainly encompass web navigation [\[27,](#page-11-10) [17,](#page-11-11) [39,](#page-12-9) [5,](#page-10-3) [14\]](#page-10-10), mobile device [\[43,](#page-12-10) [44,](#page-12-11) [24,](#page-11-12) [25,](#page-11-6) [30\]](#page-11-13), and computer desktop [\[34,](#page-12-5) [32,](#page-11-0) [7,](#page-10-12) [13\]](#page-10-13). One trend of recent advanced benchmarks is to provide an executable simulation environment. Multimodal agents can explore and interact with this platform through keyboard, mouse, gesture and touch screen actions in a more realistic and complex scenario. However, previous literature mostly focuses on daily life applications (*e.g.*, Web browser and calendar) [\[35,](#page-12-12) [23\]](#page-11-14) or workflows of nonspecialized business tasks [\[31\]](#page-11-15). Few works [\[6,](#page-10-9) [34,](#page-12-5) [31\]](#page-11-15) investigate the capability of multimodal agents to manipulate enterprise-level software. GUIs of professional applications often contain abundant domain-specific terminologies (*e.g.*, "*materialization*" in Dagster), which requires multimodal agents to understand the specialized knowledge. Spider2-V incorporates 20 professional tools into a real-time computer environment to test the proficiency of agents in data science and engineering. Furthermore, we supplement a large volume of documents for retrieval to compensate for deficiencies of agents in domain knowledge.

6 Conclusion

In this work, we propose Spider2-V, the first data science and engineering benchmark which integrates enterprise professional applications and supports intensive GUI operations besides code writing across the full data pipeline. It contains 494 tasks, involves 20 professional tools, and provides a real-time executable computer environment. The most advanced VLM (GPT-4V) still performs poorly on Spider2-V (achieving 14.0% success rate), rendering it a very challenging benchmark. Although current multimodal agents are still far from automating data workflows, Spider2-V presents an easily accessible benchmark and lays the foundation for future research.

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A Relevant URLs

Figure 8: Overview of Spider2-V, which includes task examples across the full data pipeline, an executable computer environment, and a document warehouse for agent retrieval.

Github Repository The task examples, environment, documents, code and experiments are publicly available in Github repository <https://github.com/xlang-ai/Spider2-V> under Apache-2.0 license. Both the environment and task examples will be maintained by the authors continuously.

Concretely, the environment code is adapted from previous work OSWORLD [\[34\]](#page-12-5), which is released under Apache-2.0 license. A non-exhaustive list of artifacts (or task examples) used in Spider2- V includes: 1) SheetCopilot [\[16\]](#page-11-1) which is released under GPL-3.0 license, 2) WorkArena [\[6\]](#page-10-9) which is distributed under Apache-2.0 license, and 3) official tutorials or guides on professional applications (e.g., dbt, Airflow, Dagster, Superset, etc.). These tutorials are free to use and publicly available. For those enterprise applications which require real accounts, namely BigQuery, Snowflake, dbt-cloud and ServiceNow, we only exploit their sandbox functions or free-trials without introducing any extra cost or privacy issues.

Project Website We also build a project website <https://spider2-v.github.io/> based on Nerfies [\[22\]](#page-11-16) template which is free-to-use and licensed under a Creative Commons Attribution-ShareAlike 4.0 International License. On this website, we provide a high-level overview of Spider2-V, the leaderboard of the benchmark and more concrete dynamic task demonstrations.

The authors declare that the benchmark collection and usage strictly obey the aforementioned licenses.

B Checklist of All Professional Software in Spider2-V

In Table [6,](#page-14-0) we list all professional tools incorporated in the Spider2-V benchmark, as well as their categories and descriptions.

C Details of Document Warehouse

C.1 Document Websites for Professional Tools

Table [8](#page-16-1) lists the official documentation websites corresponding to different software. We crawled only the English documentation from each official website and selected documents matching the version installed in our testing environment for download. We used $HTTrack$, a free and easy-to-use offline browser utility, to download the HTML files to a local directory, building all directories recursively.

⁷ <https://www.httrack.com/>

Table 6: Summary of all applications in Spider2-V (label \heartsuit means a real account is needed).

We also retained the directory structure of each website, as we believe the path of each document can, to some extent, represent the document's purpose. For example, the HTML files under the path "docs.getdbt.com/docs/deploy" are about deploying dbt in production or staging environments. This crawling step resulted in a total of 21, 239 HTML files.

C.2 Filtering of HTML pages

We further filtered the crawled HTML pages based on two criteria: irrelevant content to software usage and pages containing invalid content. For the former, we mainly judged whether the page contained content related to software usage based on its path and manually confirmed it. For example, pages under "author" on the website often relate to the website developer or development team rather than software usage. Additionally, we removed category-type pages that only contained navigation information. Furthermore, we filtered out pages based on the number of tokens obtained by whitespace tokenization. We mainly removed pages with token counts less than 100, as we found that these pages predominantly contained invalid information such as access failures, invalid links, or webpage redirections. For example, the official website of Dagster contained numerous links to unreleased versions of documents, all of which resulted in access failures. Therefore, after removal, the number of valid pages corresponding to Dagster decreased from 10,065 to 332. Finally, We obtained 11, 231 filtered HTML files (see Table [8\)](#page-16-1).

C.3 HTML Preprocessing

HTML files contain a significant amount of content unrelated to the actual content of the webpage, such as "<script>", "<style>" tags, tag attributes, and developer comments. These parts may provide aesthetics to the page but are irrelevant to the document-level information. Additionally, they often occupy a large portion of the HTML file, making it excessively long for LLMs to input. To perform Retrieval-Augmented Generation (RAG) more efficiently and to help models better understand software documentation, we preprocessed these HTML files in three formats: plain text, HTML, and Markdown. These three formats of data and the original HTML files will be released to facilitate future research. The token statistics of all data formats are shown in Table [9.](#page-17-0) We describe the preprocessing details below:

Plain Text: We used BeautifulSoup4 8 8 to extract the textual elements from the HTML DOM 9 9 tree and connected these elements using "\n". This method allows us to obtain the HTML content in the simplest manner, but losing the structural information of the HTML may affect the model's understanding of the webpage content.

Simplified HTML: We remove all sub-trees of the HTML DOM which do not contain textual elements. We also filter out all *headers, footers, copyrights, forms, and iFrames.* We removed all HTML tag attributes since they mostly do not contain actual content or semantic information. Additionally, when a node in the HTML DOM tree has only one child node, we remove that node and directly connect its child node to its parent node. This effectively simplifies the structure and depth of the HTML. The simplified HTML preserves both the structure and content information of the original HTML with fewer tokens.

Markdown: We further used the markdownify 10 tool to convert the simplified HTML into Markdown format. Markdown format uses fewer tokens to represent structural information compared to HTML, striking a good balance between HTML and plain text formats. Moreover, since pure text includes a substantial number of newline characters used to concatenate text elements and some parts of the text content in markdown files are directly concatenated without these newlines, this results in a smaller average number of tokens in markdown files compared to the pure text format.

Concrete examples of these three formats are detailed in the task prompts (see App. [G.3\)](#page-31-0). In our pilot experiments (see Table [7\)](#page-16-2), we compare the performances using different formats of retrieved documents on a subset (130 task samples) of Spider2-V. And pure text format outperforms the others.

 8 <https://beautiful-soup-4.readthedocs.io/en/latest/>

⁹The Document Object Model (DOM) is an interface that represents an HTML document as a tree structure, where each node is an object corresponding to a part of the document.

 10 <https://github.com/matthewwithanm/python-markdownify>

Table 7: Performances with different formats of retrieved documents on a subset of Spider2-V.

RAG Format	Success Rate $(\%)$
Pure Text	16.92
Markdown Syntax	15.38
Simplified HTML	15.38

Table 8: Summary of software documentation. OrigPageNum: The number of all web pages we crawled from the documentation website. FilteredPageNum: The number of web pages obtained after filtering out irrelevant or invalid pages.

D Details of Executable Environment in Spider2-V

In this section, we briefly introduce OSWORLD [\[34\]](#page-12-5) and how we adapt it to meet our requirements.

D.1 Overview

Spider2-V formalizes the interaction with a Ubuntu desktop as a partially observable Markov decision process (POMDP) (S, O, A, T, R) with state space S, observation space O, action space A, state transition function $T : \mathcal{S} \times \mathcal{A} \to \mathcal{S}$ and reward function $\mathcal{R} : \mathcal{S} \times \mathcal{A} \to \mathbb{R}$. Given the current observation $o_t \in \mathcal{O}$ from the desktop, the agent needs to predict action $a_{t+1} \in \mathcal{A}$ for the next step. An admissible action incurs a change in the latent state space $s_{t+1} \in S$, and the environment feedback o_{t+1} . The interaction loop repeats until a special "DONE" or "FAIL" action is issued, wherein the task episode ends and a reward $r = \mathcal{R}(s_T) \in \{0, 1\}$ is computed, with 1 indicating task success.

The executable computer environment (a Ubuntu operating system) is built upon virtual machines (VMs). By using the "*snapshot*" functionality of VM, the localhost environment state can be

Software	OrigHTML	PlainText	SimpHTML	Markdown
dbt/dbt-cloud	17954	1669	2963	1510
Dagster	131777	2615	4704	2290
Airflow	35011	2007	3885	1829
Airbyte	30124	2448	4328	2329
Superset	10798	1398	2389	1415
Metabase	33523	2288	4690	2333
Snowflake	105155	1750	3342	1595
Bigquery	103748	6245	11777	5718
Jupyter	224153	11240	19917	6743
Total	109119	4273	7789	3212

Table 9: Average number of page tokens of different documentation formats. We used TikToken, a fast BPE tokenizer for use with OpenAI's models, to calculate the token count for gpt-3.5-turbo.

Type	Use case
click	{"type": "click", "x": 12, "y": 46}
move	{"type": "move", "x": 68, "y": 90}
scroll	${'type": "scroll", " clicks": 4}$
drag	${\texttt{'type'}}:$ "drag", "x": 71, "y": 59}
press	{"type": "press", "key": "enter"}
hotkey	{"type": "hotkey", "keys": ["ctrl", "c"]}
typing	{"type": "typing", "text": "ls -lh"}
	(2) JSON dict

Figure 9: Overview of the executable environment of Spider2-V and two types of action space.

completely recovered to a stored history state. This snapshot with task-specific setup functions (see § [2.2\)](#page-2-1) serve as the initial state $s_0 \in S$ for different tasks. And a core *controller* is responsible for grounding action a_t (see App. [D.2\)](#page-17-1) into the VM desktop and obtaining observations o_t (see App. [D.3\)](#page-18-1) from the resulting state of VM. After the agent issues a special action "DONE" or "FAIL", the controller will invoke the customized evaluation function for the current task (see \S [2.3\)](#page-3-3) and report the metric score. The entire procedure is shown in Figure [9\(](#page-17-2)a).

D.2 Action Space

For generic actions that support both CLI and GUI, we introduce two different action spaces:

pyautogui code This action space accepts arbitrary executable python code. Particularly, code snippets that using python library "pyautogui" to control the mouse and keyboard are strongly recommended. Generally, mouse-based actions (*e.g.*, click and scroll) directly manipulate the GUI screen, while keyboard-based actions (*e.g.*, typewrite and hotkey) interact with the CLI such as the bash terminal and code editor (*e.g.*, Visual Studio Code).

JSON dict Inspired by the "pyautogui" library, we summarize 7 actions to simplify the action space. This small set can cover all CLI and GUI actions needed on the desktop. For each action and its parameters, we further encapsulate it into a JSON dict to restrict the output format. The API specification and use cases are formally described in prompt messages (see App. [G.1.2\)](#page-27-0). And the checklist of all 7 actions is presented in Figure [9\(](#page-17-2)b).

D.3 Observation Space

Figure 10: Two observation types: screenshot and accessibility tree (a11ytree).

With respect to observations, there are two widely used alternatives (see Figure [10\)](#page-18-2): 1) image-style screenshot of the entire desktop, and 2) text-format accessibility tree (a11ytree). The accessibility tree, obtained from the Assistive Technology Service Provider Interface (ATSPI) library 11 11 11 , is a text-format abstraction of the entire computer desktop which describes the name, type, status (*e.g.*, a menu bar is "*selectable*"), position (*e.g.*, in Figure [10](#page-18-2) (2), the attributes "*coord*" and "*size*" together define the rectangle position), and text content embedded in each element (e.g., windows, panels, buttons, and input boxes). We extract a11ytree using python library pyatspi and convert it into the XML format. It functions similar to DOM (Document Object Model) tree for websites.

D.3.1 Two tricks: Set-of-Mark and Execution Feedback

Figure 11: Screenshot with bounding boxes.

Figure 12: Converted table of a11ytree.

Figure 13: Illustration of the aligned observation type set-of-mark (SoM).

Set-of-Mark (SoM) The original text-style accessibility tree (a11ytree) and image-style screenshot do not align with each other. To compensate for this deficiency, we follow OSWORLD [\[34\]](#page-12-5) and WebArena [\[45\]](#page-12-4) to draw bounding boxes for elements of interest in the screenshot and label these elements with numeric indexes. The accurate coordinates of these bounding boxes are extracted from the a11ytree. Furthermore, we re-organize the a11ytree into a table (each leaf node in a11ytree is converted into one row) and insert another attribute/column "index" for each node in the tree. The value of attribute "index" is exactly the numeric label of the corresponding element in the screenshot. The aligned screenshot and a11ytree (*a.k.a.*, set-of-mark, SoM [\[36\]](#page-12-6)) are illustrated in Figure [13.](#page-18-4)

¹¹<https://docs.gtk.org/atspi2/>

```
Examples of Execution Feedback Messages
```

```
Here are failed actions with their error messages in your last response:
# Action 1
import pyautogui
index_34 = (23, 43)pyautogui.click(index_343)
# Execution error:
Traceback (most recent call last):
NameError: name 'index_343' is not defined
# Action 2
import pyautogui
import time
pyautogui.write('USE DATABASE IMDB\n\\n')
# Execution error:
File "<string>" line 3
pyautogui.write('USE DATABASE IMDB
                 \hat{\phantom{1}}SyntaxError: unterminated string literal
```
Execution Feedback We also incorporate another type of information as the observation, namely the *execution feedback* of actions (see messages above). We notice that, some predicted actions may be parsed erroneously or fail to be executed. In this case, the two observation types mentioned before are not changed at all. And the agent repeatedly urges to conduct the same incorrect action. To inform the agent of execution errors, we include this execution feedback as the third observation type.

E Format of Task Examples

In this section, we briefly introduce the format of task examples. Following OSWORLD [\[34\]](#page-12-5), each task instance is represented as a JSON dictionary which contains the following fields: (see Figure [14\)](#page-20-0)

- id: globally unique id of the current task example.
- instruction: the task instruction which indicates the task goal.
- source: a list of referenced tutorial links to construct the current task.
- config: a list of dictionaries which define the operations to initialize and reset the computer desktop. Each dictionary contains the function name (the "type" key) and its parameters (the "parameters" key) indicating one environment setup function. For example, in Figure [14,](#page-20-0) we define 3 environment reset functions, namely 1) "bigquery_init" to clear the cloud workspace of Google project "bigquery-project", 2) "google_chrome_browser" to launch the Google Chrome application, and 3) "bigquery_login" to simulate the Google account login operation with playwright.
- related_apps: a list of application names which should be used in the current task.
- tags: a list of tags denoting different categories.
- evaluator: a dictionary containing 3 fields: func, result, expected. It defines how to evaluate the final results once task completion. Concretely, the "func" field defines the name of our customized function (or metric) which is used to compare the predicted result and the expected golden result. The "result" field defines how to extract the predicted result from the final environment states. And the "expected" field defines how to obtain the golden result. For example, in Figure [14,](#page-20-0) we utilize the function "compare_csv" to compare the predicted file "/home/user/Downloads/answer.csv" in the virtual machine and the golden file "answer_gold.csv" in local host.

Figure 14: The format of a simple task example (.json configuration file).

F Task Examples

In this part, we present diverse examples in Spider2-V.

Table 10: Real task examples from Spider2-V.

Continued on next page

Table 10 – continued from previous page

G Prompts for Multi-modal Agents

Multi-modal agent baseline involves complex prompt engineering. The following sections will introduce the system prompt, task prompt, and retrieved context augmented prompt.

G.1 System Prompt

The entire system prompt consists of the environment prompt, observation space prompt, action space prompt, and general tips. Different action/observation types have different prompts. In this section, we will introduce each one in turn and present the overall system prompt at last.

G.1.1 Observation Space Prompt

The four different observation space settings, namely 1) screenshot, 2) a11ytree, 3) screenshot+a11ytree, and 4) SoM, each has a different prompt.

Screenshot Setting

After each action step, you will get an image-style observation, \rightarrow which is the screenshot of the computer screen. And you need to \rightarrow predict the next action on the computer based on this image.

Accessibility Tree Setting

```
After each action step, you will get a text-style observation, which
\rightarrow is extracted and pruned from the accessibility tree based on
\rightarrow \, AT-SPI library. The accessibility tree describes the elements
   (e.g., panels, icons, buttons, frames, windows, applications) on
\rightarrow the computer desktop, as well as its embedded text content,
\rightarrow status and positions. For simplicity, we prune the original tree
\rightarrow and only extract useful information into a tabular format for you.
\rightarrow Here is a quick glance on the observation:
\hookrightarrowTAG, NAME, POSITION (top-left x & y), SIZE (width & height), TEXT
menu, Visual Studio Code, (99, 0), (184, 27), ''
push-button, Chromium Web Browser, (0, 33), (70, 64), ''
terminal, Terminal, (70, 74), (1430, 832), '(base)
,→ user@ubuntu:~/projects/$'
... more rows ...
, where `TAG` / `NAME` is the element type / name respectively.
\rightarrow `POSITION` and `SIZE` together describe the square position of
\rightarrow this element on the computer screen. For example, if you want to
   click one button, you can click any point in the square area
   defined by `POSITION` and `SIZE`. Assume that the position of
\rightarrow this button is (100, 200), and the size is (40, 40), the CENTER
\rightarrow  of this button is (120, 220), which is calculated by x = 100 + 40
\rightarrow / 2 = 120, y = 200 + 40 / 2 = 220. `TEXT` refers to the text
\rightarrow content embedded in the element, e.g., the bash terminal output
\rightarrow or texts in an editable input box.
\hookrightarrow\hookrightarrowAnd you will predict the next action of the computer based on the
\rightarrow accessibility tree.
```
Screenshot + Accessibility Tree Setting

```
The observation space is a combination of two sources: 1) image-style
\rightarrow screenshot of the desktop, and 2) text-style accessibility tree
\rightarrow derived from AT-SPI library.
### Screenshot
After each action step, you will get a image-style observation, which
\rightarrow is the screenshot of the computer screen. And you need to predict
\rightarrow the next action on the computer based on this image. You can use
\rightarrow this image to locate the elements on the screen or check the
\rightarrow status of the computer, especially whether the previous action is
\rightarrow successful or not.
### Accessibility Tree
The accessibility tree describes the elements (e.g., panels, icons,
\rightarrow buttons, frames, windows, applications) on the computer desktop,
\rightarrow as well as its embedded text content, status and positions. For
\rightarrow simplicity, we prune the original tree and only extract useful
\rightarrow information into a tabular format for you. Here is a quick glance
\rightarrow on the observation:
TAG, NAME, POSITION (top-left x & y), SIZE (width & height), TEXT
menu, Visual Studio Code, (99, 0), (184, 27), ''
push-button, Chromium Web Browser, (0, 33), (70, 64), ''
terminal, Terminal, (70, 74), (1430, 832), '(base)
,→ user@ubuntu:~/projects/$'
... more rows ...
, where `TAG` / `NAME` is the element type / name respectively.
\rightarrow `POSITION` and `SIZE` together describe the square position of
\rightarrow this element on the computer screen. For example, if you want to
\rightarrow click one button, you can click any point in the square area
\rightarrow defined by `POSITION` and `SIZE`. Assume that the position of
\rightarrow this button is (100, 200), and the size is (40, 40), the CENTER
\rightarrow  of this button is (120, 220), which is calculated by x = 100 + 40
\rightarrow / 2 = 120, y = 200 + 40 / 2 = 220. `TEXT` refers to the text
\rightarrow content embedded in the element, e.g., the bash terminal output
\rightarrow or texts in an editable input box.
You can use the accessibility tree to accurately locate positions of
\rightarrow useful elements on the screen and check the concrete textual
\leftrightarrow contents of elements.
By combining the screenshot and accessibility tree, you should be
\rightarrow intelligent to predict the next feasible and meaningful action.
```
SoM Setting

The observation space is a combination of two sources: 1) image-style \rightarrow screenshot of the desktop with interact-able elements marked with \rightarrow -numerical indexes, and 2) text-style accessibility tree derived \leftrightarrow from AT-SPI library. ### Labeled Screenshot After each action step, you will get a image-style observation, which \rightarrow is the screenshot of the computer screen. For ease of locating \rightarrow positions of elements, we extend the original screenshot with \rightarrow index marks. That is, some salient elements which can be \rightarrow interacted with (e.g., a button or editable input box) are marked \rightarrow with line boudaries and numeric indexes. You can use this image \rightarrow to locate the elements on the screen or check the status of the \rightarrow computer, especially whether the previous action is successful or \hookrightarrow not. ### Accessibility Tree The accessibility tree describes the elements (e.g., panels, icons, \rightarrow buttons, frames, windows, applications) on the computer desktop, \rightarrow as well as its embedded text content, status and positions. For \rightarrow simplicity, we prune the original tree and only extract useful \rightarrow information into a tabular format for you. Here is a quick glance \rightarrow on the observation: INDEX, TAG, NAME, POSITION(top-left x & y), SIZE(width & height),TEXT 1, menu, Visual Studio Code, (99, 0), (184, 27), '' 2, push-button, Chromium Web Browser, $(0, 33)$, $(70, 64)$, 3, terminal, Terminal, (70, 74), (1430, 832), (base) user@ubuntu:~/projects/\$' ... more rows ... , where `INDEX` indicates exactly the numeric label for each element \rightarrow marked in the screenshot. You can use this alignment information \rightarrow to simplify your predicted action. For example, you can use \rightarrow `pyautogui.click(index_2)` to represent clicking the CENTER of \rightarrow the element with index 2 on the screenshot. We will automatically \rightarrow perform the position calculation and substitution for you. `TAG` \rightarrow / `NAME` is the element type / name respectively. `POSITION` and `SIZE` together describe the square position of this element on \rightarrow the computer screen. For example, if you want to click one button, \rightarrow you can click any point in the square area defined by `POSITION` \rightarrow and `SIZE`. Assume that the position of this button is (100, 200), \rightarrow and the size is (40, 40), the CENTER of this button is (120, 220), \rightarrow which is calculated by x = 100 + 40 / 2 = 120, y = 200 + 40 / 2 = 220. `TEXT` refers to the text content embedded in the element, \rightarrow e.g., the bash terminal output or texts in an editable input box. \hookrightarrow \hookrightarrow You can use the accessibility tree to accurately locate positions of \rightarrow useful elements on the screen and check the concrete textual \leftrightarrow contents of elements. By combining the screenshot and accessibility tree, you should be \rightarrow intelligent to predict the next feasible and meaningful action.

G.1.2 Action Space Prompt

As for the prompt of action space, we provide two choices: 1) pyautogui code, and 2) JSON dict.

pyautogui Code

```
You are required to use `pyautogui` to perform the action grounded to
\leftrightarrow the observation. And the action space includes two types:
1. Python code block using pyautogui wrapped by 3 backticks, e.g.,
  `python
# you python code here, e.g.,
pyautogui.hotkey('ctrl', 'c')
\ddot{\phantom{0}}2. Three pre-defined special actions: [WAIT, FAIL, DONE]
- When you think you have to wait for some time, return ```WAIT```;
- When you think the task can not be done, return ```FAIL```, don't
,→ easily say ```FAIL```, try your best to do the task;
- When you think the task is done, return ```DONE```.
These 3 actions also need to be wrapped by 3 backticks.
### REMEMBER THAT:
0. We will import libraries `pyautogui` and `time` automatically for
\rightarrow you, but if you use other python libraries, PLEASE IMPORT THEM
\rightarrow FIRST ALTHOUGH THIS IS DISCOURAGED;
1. DONOT use the `pyautogui.locateCenterOnScreen` function to locate
\rightarrow the element you want to operate with, since we have no image of
\rightarrow the element you want to operate with;
2. DONOT use the `pyautogui.screenshot` function to make screenshot;
3. For time efficiency, you can return one line or multiple lines of
\rightarrow python code to perform continuous actions in one response. For
\leftrightarrow example, your response may contain the following code block:
\ddot{\phantom{0}}pyautogui.moveTo(100, 210)
pyautogui.dragTo(500, 200, button='left', mouseDownUp=True)
pyautogui.rightClick()
\ddot{\phantom{0}}4. When predicting multiple lines of code, make some small delay like
\rightarrow `time.sleep(0.5)` interval, such that the machine can response
\rightarrow correctly. And it is STRONGLY RECOMMENDED that, for one action
\rightarrow which may influence the environment significantly (e.g., click
\rightarrow the button of one application to open it, or click a web link
\rightarrow which navigates to a new page), it is better to predict this
\rightarrow action without follow-ups in order to observe the changes in
\leftrightarrow environment states first;
5. Each time when you predict code, neither variables nor function is
\rightarrow shared acrossed different code blocks. In other words, each code
\rightarrow block will be executed in isolation;
6. For coordinates (x, y), please speculate or calculate by yourself
\rightarrow based on the observation of previous interaction turn. BE CAREFUL
\leftrightarrow to ensure the coordinates are feasible.
7. Please pay attention that, code wrapped by 3 backticks ``` will be
\rightarrow recognized as an action in the action space. Therefore, when you
\rightarrow output non-action code, please use other symbols like '''
\leftrightarrow instead.
```
JSON Dict (truncated)

```
Firstly, we use json dict to describe the types and parameters for
\rightarrow each action we allowed (`required=true` means this argument must
\rightarrow be provided). Then, we demonstrate use cases, and precautions.
### Specification for All Actions
ACTION_LIST = [
    {
        "action_type": "MOVE_TO",
        "note": "move the cursor to a specified position (x, y)",
        "parameters": {
             "x": {
                 "type": float,
                 "range": [0, MAX_SCREEN_WIDTH],
                 "required": true,
             },
             "y": {
                  "type": float,
                 "range": [0, MAX_SCREEN_HEIGHT],
                 "required": true,
             }
        }
    },
    ... more action dicts ...
]
### Use Cases
- For MOVE_TO, you need to predict the x and y coordinate of the
\rightarrow mouse cursor, the left top corner of the screen is (0, 0).
Use case: move the mouse to position (56.1, 65.0)
  ```json
{
 "action_type": "MOVE_TO",
 "x": 56.1,
 "y": 65.0
}
... more use cases ...
Precautions
1) The output action MUST BE CHOSEN and CAN ONLY BE CHOSEN from the
\rightarrow \, action space (json dict) defined above, otherwise your action
\rightarrow will be considered as invalid and you will get a penalty. For
\rightarrow example, bash, sql, or python code WILL NOT be executed;
2) For each action dict, STRICTLY OBEY THE FORMAT, which must contain
\rightarrow the `action_type` field and required parameters. Optional
\rightarrow parameters will be set to default values if not provided. NEVER
\rightarrow RETURN ME ANYTHING ELSE WHICH IS NOT DEFINED;
3) For efficiency, you CAN predict multiple actions in one response,
\hookrightarrow but REMEMBER TO WRAP EACH ACTION DICT SEPARATELY using backticks
   ```json and ```.
\hookrightarrow
```
G.1.3 Overall System Prompt

```
You are an intellignet agent who is expert in completing data
science/engineering tasks using professional tools on computer. You
\rightarrow have deep understanding of computer basics and data
\leftrightarrow science/engineering knowledge.
Now, you will interact with a real desktop environment, which is an
\rightarrow Ubuntu operating system that has access to the Internet. You
\rightarrow should strictly follow the user instruction, communicate with the
\rightarrow environment and try your best to complete the given data-related
\rightarrow task successfully. Generally, you will communicate with the
   environment in this interactive and continuous manner:
\hookrightarrow1) In each iteration, you should take one action to control the
\leftrightarrow keyboard or mouse in the desktop environment given the actions
\rightarrow and observations from a few previous steps;
2) Then, you will obtain new observations from the environment after
\rightarrow the action is grounded (you do not need to worry about the
\rightarrow execution, we will perform it for you);
3) Repeat steps 1) and 2) until you think the work is done.
Here are the details of the action spaces (including usage and
\rightarrow precautions) and observation spaces:
{{action_prompt}}
{{observation_prompt}}
Besides, here are some important tips for you to better complete the
\leftrightarrow task:
1. My computer's password is 'password', feel free to use it when you
\rightarrow need sudo rights.
2. The screen size for the running desktop is: ({screen_width},
\rightarrow {screen_height}).
3. Some action may need time to reflect in the environment (e.g.,
\rightarrow \, code execution and web page loading), please be patient and refer
\rightarrow to the WAIT action.
4. Try to complete the task in as few steps as possible, we are on a
\rightarrow tight budget.
5. Try to use the applications we opened for you as possible, e.g.,
\rightarrow use the opened gnome-terminal instead of the embedded one in
\rightarrow Visual Studio Code.
6. For critical actions (e.g., opening an application or clicking a
\leftrightarrow button), ensure the action succeeds before predicting or
\rightarrow proceeding to the next one. That is, DO NOT be greedy to predict
\rightarrow all actions all at once in one response without confirming the
\rightarrow observation of a significant action.
7. When you try to write codes or texts, please ensure you have
\rightarrow focused on the right window or input panel. If the input panel
\rightarrow already has some texts, be careful that you may need to clear or
\rightarrow selecting them before overwritting.
8. DO NOT be stubborn to complete the task in one step. You can break
\rightarrow down the task into several steps and complete them one by one.
9. DO NOT be stupid to repeat the same actions without any progress.
\rightarrow If you find that the action is not effective in the observation,
\rightarrow try another one.
10. RETURN ME ONLY THE ACTION DEFINED IN ACTION SPACES. NEVER EVER
\rightarrow RETURN ME ANYTHING ELSE. THIS IS CRITICAL!!!
```
G.2 Task Prompt

The task instruction for Spider2-V has two forms. The abstract instruction describes the overall goal of a task without a step-by-step solution, thus testing both planning and grounding abilities. The verbose instruction provides a detailed tutorial-like solution to the task, primarily validating the grounding ability.

G.2.1 Example of Task Prompt for Abstract Instructions

```
Now, let's start the task!
You are asked to complete the following task: I want to build an
\rightarrow airflow project connecting to a local postgres database. Could
    you install docker, astro and postgresql for me. The sudo
\rightarrow password is 'password' (' not included). By the way, configure
\rightarrow docker and postgresql to auto-start on boot, and allow me to
\rightarrow prevent typing sudo when using docker each time.
\hookrightarrow
```
G.2.2 Example of Task Prompt for Verbose Instructions

```
Here is a step-by-step tutorial from an expert instructing you how to
\leftrightarrow complete it:
Now we want to upload data from xlang_gcs/google_ads/ in google cloud
\rightarrow storage to my dataset google_ads. To do this:
1. Click the "+ ADD" button next to the "Explorer" panel.
2. Click the "Google Cloud Storage" panel on the pop-up window.
3. In the input box "Google Cloud Storage", enter the
\rightarrow 'xlang_gcs/google_ads/account_history_data.csv' in the second
\rightarrow windows. This window is labeled 'Select file from GCS bucket or
\leftrightarrow use a a URI pattern'.
4. Destination Part, set Dataset to 'my_google_ads'
5. In Destination Part, set Table to 'account_history_data'
6. In Schema part, Mark the check mark in front of Auto detect.
7. Then, click the blue `CREATE TABLE` button at the bottom.
8. After page loading, click the "+ ADD" button next to the
\rightarrow "Explorer" panel again.
9. Click the "Google Cloud Storage" panel on the pop-up window.
10. In the input box "Google Cloud Storage", enter the
   'xlang_gcs/google_ads/account_stats_data.csv' in the second
\rightarrow windows. This window is labeled 'Select file from GCS bucket or
\leftrightarrow use a a URI pattern'.
\hookrightarrow11. Destination Part, set Dataset to 'my_google_ads'
12. In Destination Part, set Table to 'account_stats_data'
13. In Schema part, Mark the check mark in front of Auto detect.
14. Click the `CREATE TABLE` button at the bottom left in the pop-up
\rightarrow window.
Eventually, we have completed this task.
You can exactly follow the detailed plan above or proactively tackle
\leftrightarrow the task based on the real-time environment interaction by
\leftrightarrow yourself.
```
G.3 Example of Retrieved Context Augmented Task Prompt

We also introduce a RAG setting, where we collect and clean the official documents of the professional tools as the retrieval corpus. We select top k (k may depend on the constraint on input length) chunks (each chunk is a token sequence with maximum length 512) and insert them into the prompt input. Here are three demonstrations of different formats of the retrieved context.

Pure Text Format

```
We also retrieve relevant documentation from the web to help you with
\leftrightarrow the task:
Documentation Source:
release-1-7-2.dagster.dagster-docs.io/integrations/dagstermill/using-
\rightarrow notebooks-with-dagster.html
Documentation Title:
Using Jupyter notebooks with Papermill and Dagster Tutorial
Documentation Content:
The page will display the notebook asset in the Asset Graph.
If you click the notebook asset, a sidebar containing info about the
\rightarrow asset will slide out from the right side of the page. In the
\rightarrow Description
section of the panel is a View Source Notebook button:
This button allows you to view the notebook directly in the UI. When
\rightarrow clicked, Dagster will render the notebook - referenced in the
notebook_path parameter - that'll be executed when the
\rightarrow iris_kmeans_jupyter asset is materialized:
Click the Materialize button. To view the execution as it happens,
\rightarrow click the View button in the alert that displays.
After the run completes successfully, you can view the executed
\rightarrow notebook in the UI. Click the asset again and locate the View
\rightarrow Notebook button in the Materialization in Last Run section of the
   sidebar:
\hookrightarrowClick the button to display the executed notebook - specifically, the
\rightarrow notebook that was executed and written to a persistent location:
Step 5: Add an upstream asset #
While our iris-kmeans notebook asset now materializes successfully,
\rightarrow there are still some improvements we can make. The beginning of
\rightarrow the notebook fetches the Iris dataset, which means that every
\rightarrow time the notebook is materialized, the data is re-fetched.
To address this, we can factor the Iris dataset into its own asset.
\rightarrow This will allow us to:
Use the asset as input to additional notebooks.
This means all notebooks analyzing the Iris dataset will use the same
\rightarrow source data, which we only have to fetch once.
Materialize notebooks without fetching data for each materialization.
Instead of making potentially expensive API calls, Dagster can fetch
\leftrightarrow the data from the previous materialization of the Iris dataset
\rightarrow and provide that data as input to the notebook.
```
Markdown Syntax Format

```
We also retrieve relevant documentation from the web to help you with
ightharpoonup the task:
Documentation Source:
release-1-7-2.dagster.dagster-docs.io/integrations/dagstermill/using-
notebooks-with-dagster.md
Documentation Title:
Using Jupyter notebooks with Papermill and Dagster Tutorial
Documentation Content:
When clicked, Dagster will render the notebook - referenced in the
 \rightarrow `notebook_path`parameter - that'll be executed when the
 \rightarrow `iris_kmeans_jupyter`asset is materialized:
!Click the **Materialize**button. To view the execution as it happens,
,→ click the **View**button in the alert that displays.
After the run completes successfully, you can view the executed
 \rightarrow notebook in the UI. Click the asset again and locate the **View
 \rightarrow Notebook**button in the **Materialization in Last Run**section of
 \leftrightarrow the sidebar:
!Click the button to display the executed notebook - specifically,
 \rightarrow the notebook that was executed and written to a persistent
 \rightarrow location:
!Step 5: Add an upstream asset#
------------------------------
While our `iris-kmeans`notebook asset now materializes successfully,
 \rightarrow there are still some improvements we can make. The beginning of
 \rightarrow the notebook fetches the Iris dataset, which means that every
 \rightarrow time the notebook is materialized, the data is re-fetched.
To address this, we can factor the Iris dataset into its own asset.
\rightarrow This will allow us to:
**Use the asset as input to additional notebooks.**This means all
 \rightarrow notebooks analyzing the Iris dataset will use the same source
 \rightarrow data, which we only have to fetch once.
**Materialize notebooks without fetching data for each
 \rightarrow materialization.**Instead of making potentially expensive API
     calls, Dagster can fetch the data from the previous
     materialization of the Iris dataset and provide that data as
 \rightarrow input to the notebook.
 \hookrightarrow\hookrightarrowIn this step, you'll:
Create the Iris dataset assetProvide the Iris dataset as input to the
\rightarrow notebookModify the notebook
```
Simplified HTML Format

```
We also retrieve relevant documentation from the web to help you with
\leftrightarrow the task:
Documentation Source:
release-1-7-2.dagster.dagster-docs.io/integrations/dagstermill/using-
notebooks-with-dagster.html
Documentation Title:
Using Jupyter notebooks with Papermill and Dagster Tutorial
Documentation Content:
If you execute these cells, several plots of the Iris dataset will be
\leftrightarrow created:
<p>Next, we conduct our K-means analysis:</p>
<code>estimator</code>
,→ <span>=</span>sklearn<span>.</span>cluster<span>.</span>KMeans
<span>(</span>n_clusters<span>=</span><span>3</span><span>)</span>
estimator<span>.</span>fit<span>(</span>iris<span>[</span>
<span>[</span><span>"Sepal length (cm)"</span><span>,</span>
<span>"Sepal width (cm)"</span><span>,</span>
<span>"Petal length (cm)"</span><span>,</span>
<span>"Petal width (cm)"</span>
<span>]</span><span>]</span><span>)</span>
\langle/code>
<p>Lastly, we plot the results of the K-means analysis. From the
 \rightarrow plots, we can see that one species of Iris is separable from the
 \rightarrow other two, but a more sophisticated model will be required to
 \rightarrow distinguish the other two species:</p>
<p>Like many notebooks, this example does some fairly sophisticated
 \rightarrow work, including producing diagnostic plots and a statistical
 \rightarrow model. For now, this work is locked away in the
 \rightarrow <code><code>.ipynb</code></code>format, only reproducible using a complex
 \rightarrow Jupyter setup, and only programmatically accessible within the
 \rightarrow notebook context. We'll address this in the remainder of the
 \leftrightarrow tutorial.\lt/p<h2>Step 2: Create a Dagster asset from the Jupyter
,→ Notebook<span>#</span></h2>
<p>By creating a Dagster asset from our notebook, we can integrate
 \leftrightarrow the notebook as part of our data platform. This enables us to
 \rightarrow make its contents more accessible to developers, stakeholders,
 \leftrightarrow and other assets in Dagster.</p>
<p>To create a Dagster asset from a Jupyter notebook, we can use the
,→ <code>define_dagstermill_asset</code>function.
```